

Edge-partitioning a graph into paths: beyond the Barát-Thomassen conjecture

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Part 1: Introduction to the problem

Part 2: Fractions of graphs

Part 3: Path-graphs

Part 4: Constructing path-trees

Part 5: Using everything together

Part 6: Conclusion

Main problem

G : undirected simple graph.

T : tree with $|E(T)|$ dividing $|E(G)|$.

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A *T-decomposition* of G is a partition E_1, \dots, E_k of $E(G)$ such that E_i induces an isomorphic copy of T for every $i = 1, \dots, k$.

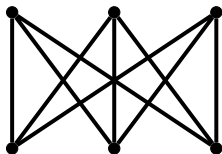
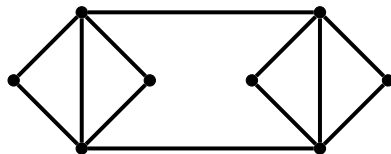
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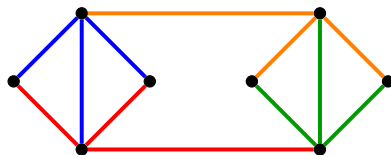
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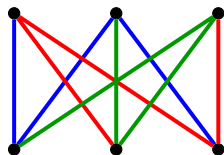
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S_4 -decomposition



P_3 -decomposition

The Barát-Thomassen conjecture

Divisibility condition is understood throughout.

Conjecture [Barát, Thomassen – 2006]

For every fixed tree T , there exists a positive constant c_T such that every c_T -edge-connected graph admits a T -decomposition.

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Verified for T being:

- a star [Thomassen – 2012],
- a bistar of the form $S_{k,k+1}$ [Thomassen – 2014],
- the tree with degree sequence $(1, 1, 1, 2, 3)$ [Barát, Gerbner – 2014],
- of **diameter at most 4** [Merker – 2015+],
- among some family of trees with diameter 5 [Merker – 2015+],

and...

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- the path of length 3 [Thomassen – 2008],
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- a **path of length 2^k [Thomassen – 2014]**,
- the path of length 5 [Botler, Mota, Oshiro, Wakabayashi – 2015],
- **any path [Botler, Mota, Oshiro, Wakabayashi – 2015+]!**

About the result for paths

Theorem [Botler, Mota, Oshiro, Wakabayashi – 2015+]

The Barát-Thomassen conjecture is true for T being any path.

About the proof:

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Our goal: give a somewhat simpler proof with *reasonable* technicalities.

A stronger result

'Stronger' = **degree** is more important than **edge-connectivity**.

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Theorem [B., Harutyunyan, Thomassé – 2015+]

For every $\ell \geq 1$, every 64-edge-connected graph admits a P_ℓ -decomposition provided its minimum degree is large enough.

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More general question

2-edge-connectivity + large minimum degree \Rightarrow path-decomposition???

Overview of the proof

Main ideas:

1. See G as a 'convenient' system H of induced paths.
2. Remove some P_ℓ 's from G so that H is eulerian.
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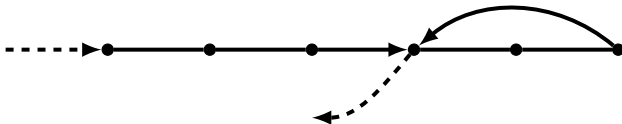
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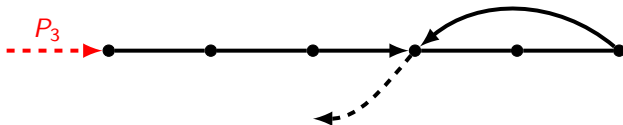
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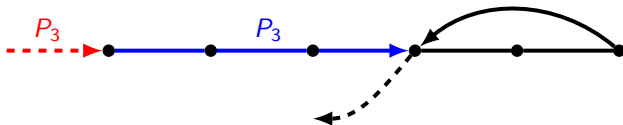
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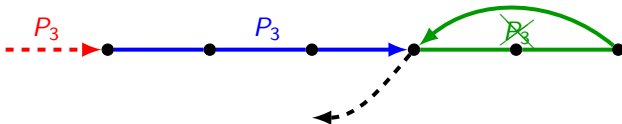
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Sparse and dense subgraphs

α : real number in $[0, 1]$.

Definitions: α -sparse, α -dense, α -fraction

Let H be a spanning subgraph of G . We say that H is α -sparse (resp. α -dense) if $d_H(v) \leq \alpha d_G(v)$ (resp. $d_H(v) \geq \alpha d_G(v)$) for every $v \in V(G)$. We say that H is an α -fraction of G if H is both α -sparse and α -dense.

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k -edge-connectivity + large degree \Rightarrow $1/k$ -sparse spanning tree.

Theorem [Ellingham, Nam, Voss – 2002]

Every k -edge-connected graph admits a $1/k$ -sparse spanning tree.

(with error term $+2$)

On fractions of graphs

Proposition

Every graph G has a $1/2$ -fraction (with error term ± 1).

Proof: If G has an even cycle C , remove the edges of C , apply induction and add the edges of a perfect matching of C to the solution. Otherwise, G is either an odd cycle (in which case the conclusion follows), or has a cutvertex z incident to an 'endblock' B which is either an edge or an odd cycle. Then contract B to z , apply induction, and extend the solution by conveniently choosing some edges of B . ■

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Corollary

If α has a finite binary extension, then G has an α -fraction.

(with constant additive error term)

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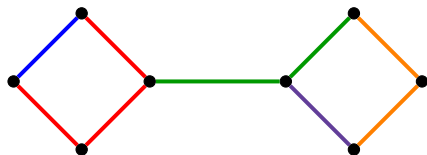
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A *path-graph* H on $G = (V, E)$ is a couple (V, \mathcal{P}) where \mathcal{P} is a set of edge-disjoint paths of G . For every $v \in V$, we define \mathcal{P}_v as the set of paths of \mathcal{P} having v as an endvertex. To H , we associate the (multi)graph H^* on vertex set V and edge set contains the pairs of endvertices of \mathcal{P} .

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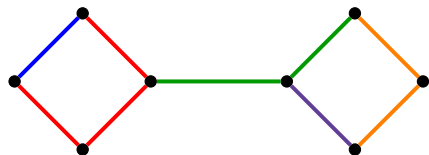


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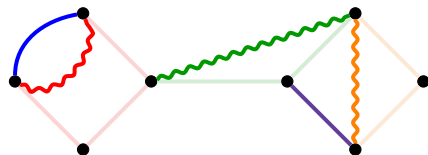
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H on G



H^*

Properties of path-graphs

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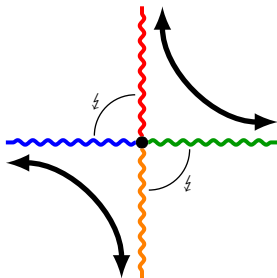
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- **H eulerian** $\Leftrightarrow H$ connected + $d_H(v)$ even for every $v \in V$.
- **H q -path-graph** \Leftrightarrow all paths of \mathcal{P} have length q .
- **H ($\leq q$)-path-graph** \Leftrightarrow all paths of \mathcal{P} have length at most q .
- **H ($\geq q$)-path-graph** \Leftrightarrow all paths of \mathcal{P} have length at least q .
- **H (q_1, q_2)-path-graph** \Leftrightarrow all paths of \mathcal{P} have length q_1 or q_2 .

Previous example: disconnected (≤ 3)-path-graph.

Conflicting paths

- **Conflicting paths** \Leftrightarrow paths sharing more than just one end.
- **Conflictless trail** \Leftrightarrow trail with no subsequent conflicting paths.
- **H conflictless eulerian** $\Leftrightarrow H$ has a conflictless eulerian closed trail.



More terminology for conflicts

Definition: *multiplicity*

For distinct $w, v \in V$, the *multiplicity* of w around v is

$$\text{mult}_v(w) := |\{P \in \mathcal{P}_v : w \in P\}| / |\mathcal{P}_v|.$$

The *multiplicity* of H is the maximum multiplicity of its vertices.

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Definitions: *conflict graph, conflict ratio*

For every $v \in V$, the *conflict graph* H_v is the graph on vertex set \mathcal{P}_v in which P_1P_2 is an edge if P_1 and P_2 intersect. The *conflict ratio* of H is defined as

$$\max\{(\Delta(H_v) + 1)/|\mathcal{P}_v| : v \in V\}.$$

Remark: Every path is self-conflicting.

Eulerian closed trails and conflict ratio

Eulerian path-graph + reasonable conflict ratio \Rightarrow conflictless eulerian closed trail.

Theorem

Every eulerian path-graph H with conflict ratio at most $1/8$ has a conflictless eulerian closed trail.

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Proof: Since the antidegree of every vertex in H_v is greater than $|\mathcal{P}_v|/2$, necessarily H_v admits a hamiltonian anticycle (by Dirac's Theorem). So there is a pairing $M_v = P_1P_2, P_3P_4, \dots$ of the paths in \mathcal{P}_v such that each pair is non-conflicting.

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Having such a pairing M_v for every $v \in V$ defines a set of conflictless closed trails T_1, \dots, T_t , where a pair $\{P_i, P_{i+1}\}$ means that when entering at a vertex via P_i , we must leave via P_{i+1} (and vice-versa). If $t = 1$, we are done. Otherwise, we merge two trails so that t decreases.

Merging two conflictless closed trails

By our terminology, there is a $v \in V$ whose some paths of \mathcal{P}_v belong to, say, T_1 . We may assume that no more than half of its paths appear in T_1 .

Assume $\{P_1, P_2\} \in M_v$ and $P_1, P_2 \in T_1$. Because P_1 and P_2 have degree less than $|\mathcal{P}_v|/8$ in H_v , there is a pair $\{P_3, P_4\}$ not in T_1 and such that P_1, P_2, P_3, P_4 are non-conflicting. Then replace $\{P_1, P_2\}$ and $\{P_3, P_4\}$ in M_v by $\{P_1, P_4\}$ and $\{P_2, P_3\}$. Then t decreases by 1, as claimed. ■

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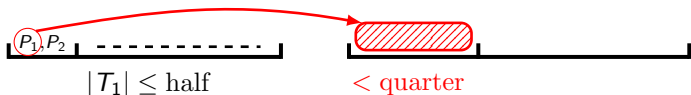
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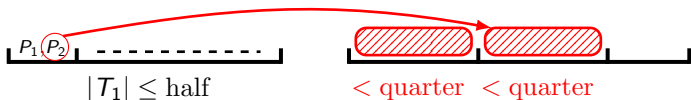
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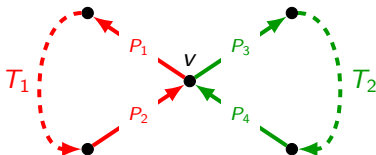
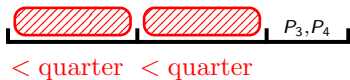
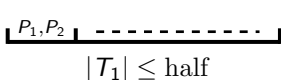
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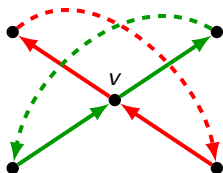
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By our terminology, there is a $v \in V$ whose some paths of \mathcal{P}_v belong to, say, T_1 . We may assume that no more than half of its paths appear in T_1 .

Assume $\{P_1, P_2\} \in M_v$ and $P_1, P_2 \in T_1$. Because P_1 and P_2 have degree less than $|\mathcal{P}_v|/8$ in H_v , there is a pair $\{P_3, P_4\}$ not in T_1 and such that P_1, P_2, P_3, P_4 are non-conflicting. Then replace $\{P_1, P_2\}$ and $\{P_3, P_4\}$ in M_v by $\{P_1, P_4\}$ and $\{P_2, P_3\}$. Then t decreases by 1, as claimed. ■



To larger paths with reasonable conflicts

Growing paths with still 'reasonable' path conflicts?

Lemma

Let q be some fixed positive integer and $c > 0$ be some real number such that $cq < 1/100$. Let $H = (V, \mathcal{P})$ be an α -dense q -path-graph of some graph G with multiplicity at most c and minimum degree k large with respect to $1/c$ and q . Then one can form an $\alpha/5$ -dense $2q$ -path-graph on G with multiplicity at most $16cq$.

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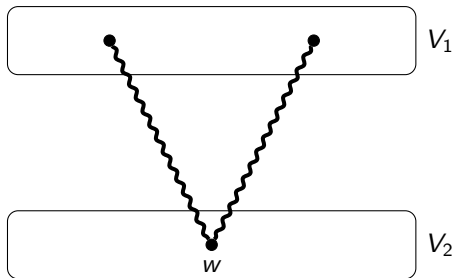
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Proof idea: Consider a cut (V_1, V_2) of V maximizing the size of the set \mathcal{P}' of edges of H^* 'between' V_1 and V_2 . Let $H' = (V, \mathcal{P}')$. Then H' is $\alpha/2$ -dense and has multiplicity at most $2c$. Now split H' into two $1/2$ -fractions $H'_1 = (V, \mathcal{P}'_1)$ and $H'_2 = (V, \mathcal{P}'_2)$. These two path-graphs are $\alpha/4$ -dense and have multiplicity at most $4c$. We use H'_1 only to form a $2q$ -path graph on V_1 with required density (almost automatic) and multiplicity (much harder).

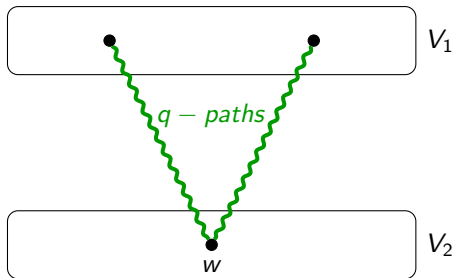
Overview of the proof

We iteratively want to randomly concatenate two q -paths meeting in V_2 at some vertex w to connect two vertices V_1 via a $2q$ -paths.



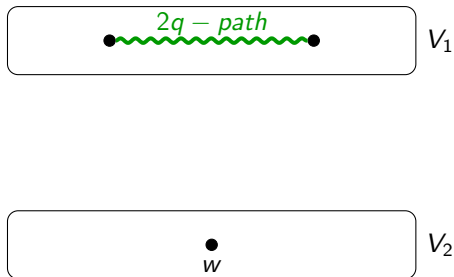
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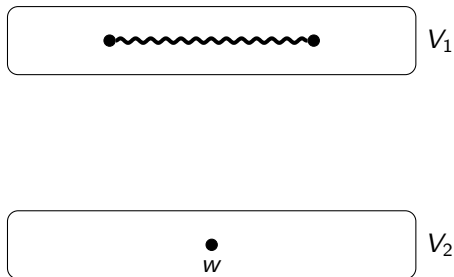
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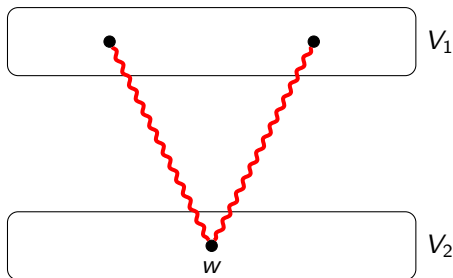
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We iteratively want to randomly concatenate two q -paths meeting in V_2 at some vertex w to connect two vertices V_1 via a $2q$ -paths.



Problem: The two paths may be conflicting, and w can have degree so large that it carries too many path dependencies (making impossible e.g. the application of Lovász Local Lemma).

Pairing non-conflicting q -paths

Solution: Group the q -paths arriving at w into small subsets of non-conflicting paths \rightarrow Possible because of the multiplicity assumption.

Generalization of Hajnal-Szemerédi Theorem

Let G be some graph of order n . Then, for every integer $t \geq \Delta(G) + 1$, the set $V(G)$ can be partitioned into V_1, \dots, V_t such that each V_i is an independent set of size $\lfloor \frac{n}{t} \rfloor$ or $\lceil \frac{n}{t} \rceil$.

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Now randomly pairing the q -paths arriving at every vertex w of V_2 , we get a $2q$ -path graph H_1'' spanning V_1 . Multiplicity around every vertex v of V_1 is shown to be smaller than $16cq$ by combining LLL and Chernoff's bound.

Using H_2' instead H_1' , we also obtain a $2q$ -path graph H_2'' spanning V_2 . ■

Constructing larger paths with reasonable conflicts

From repeated applications, we get:

Theorem

Let p be some integer and $0 < c < 1$ be some real number. There is an integer k depending on p and c such that every graph G with minimum degree at least k admits a $1/5^p$ -dense 2^p -path graph H with multiplicity at most c .

Part 1: Introduction to the problem

Part 2: Fractions of graphs

Part 3: Path-graphs

Part 4: Constructing path-trees

Part 5: Using everything together

Part 6: Conclusion

Constructing $(1, \ell)$ -trees

2-edge-connectivity + large degree $\Rightarrow (1, \ell)$ -(path-)tree with 'small' degree.

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Every 2-edge-connected graph G admits a subcubic spanning $(1, 2)$ -tree.

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To every vertex v of G , we initially associate the empty $(1, 2)$ -tree X on $\{v\}$. The procedure mainly consists in iteratively considering vertices at the highest depth, and 'merging' their corresponding $(1, 2)$ -trees somehow. This is done with preserving 2-edge-connectivity.

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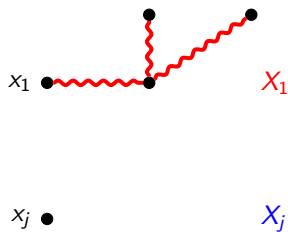
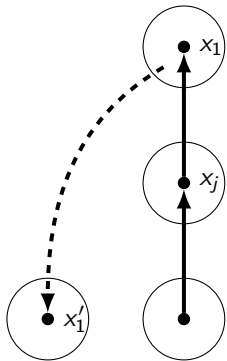
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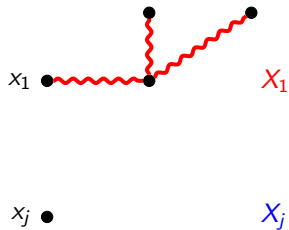
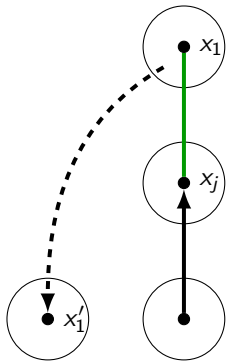
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The key to respect the degree condition is that there are only two possibilities for increasing the degree of a vertex in a merged $(1, 2)$ -tree, namely by adding its incident forward and backward edges. ■

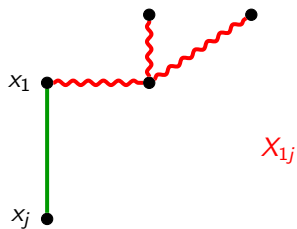
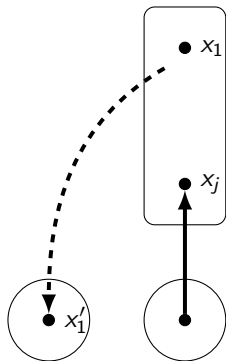
Sample cases – One child



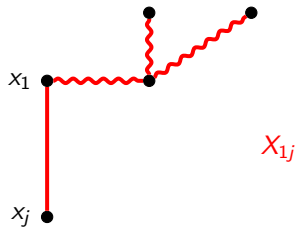
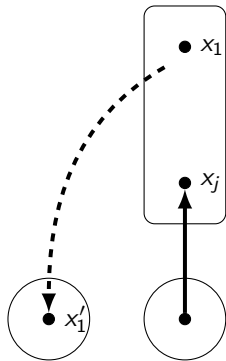
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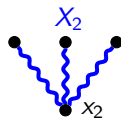
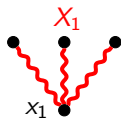
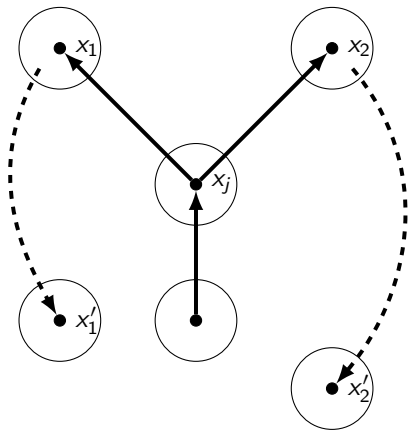
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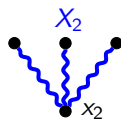
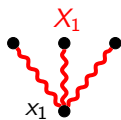
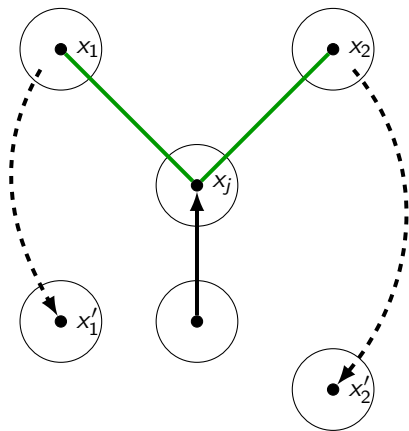
Sample cases – Two children



x_j ●

x_j

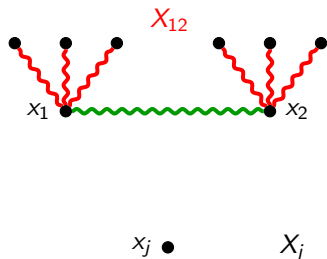
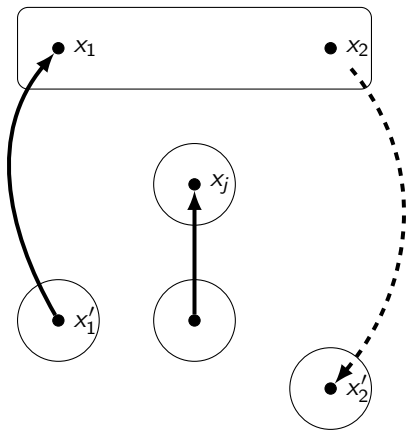
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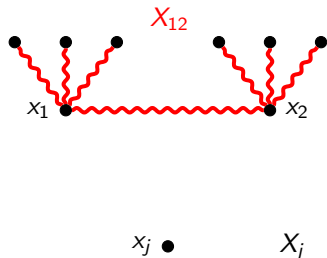
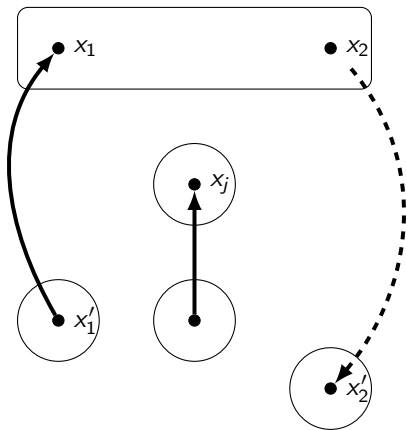
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From $(1, 2)$ -trees to $(1, k)$ -trees

spanning $(1, k)$ -tree + disjoint 'source' of degree = spanning $(1, k + 1)$ -tree.

Theorem

Let T be a spanning $(1, k)$ -tree of some graph $G = (V, E)$, and let H be some additional graph on V , edge-disjoint from G , and satisfying $d_H(v) \geq 2(d_T(v) + 2k)$ for every $v \in V$. Then $G \cup H$ is spanned by a $(1, k + 1)$ -tree T' .

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Proof idea: Same kind of proof. Start from the leaves of T and iteratively concatenate incident k -paths of T with some edges of H in order to form $(k + 1)$ -paths. This is always possible by the assumption on the degrees in H .

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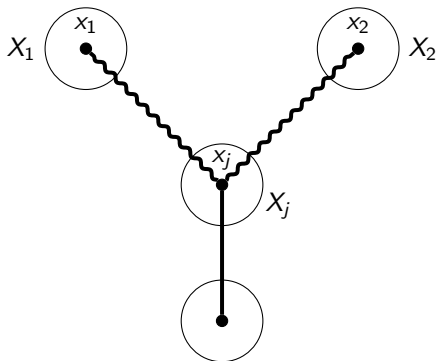
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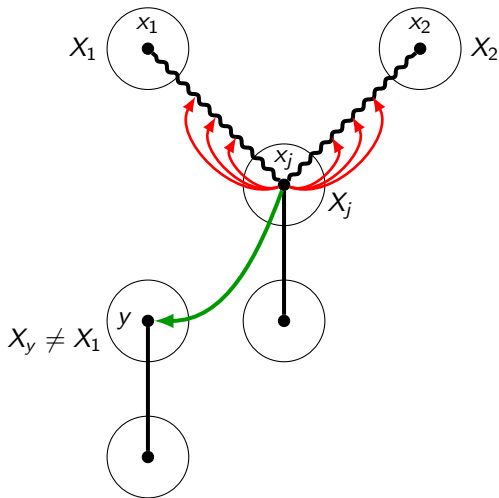
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To make sure that the edges of H are equitably used and not 'saturated' by some vertex, we orient them in a balanced way beforehand (hence defining *private edges* for every vertex). ■

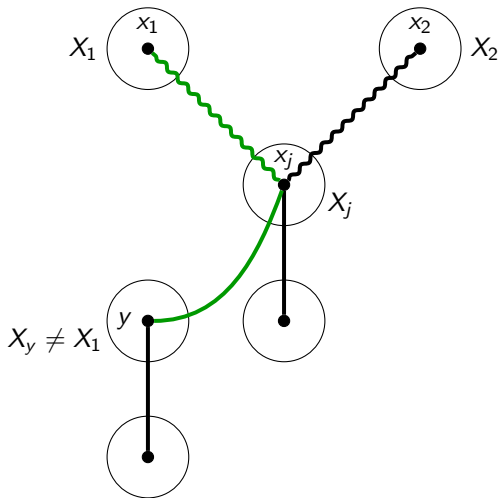
Sample case – Two children



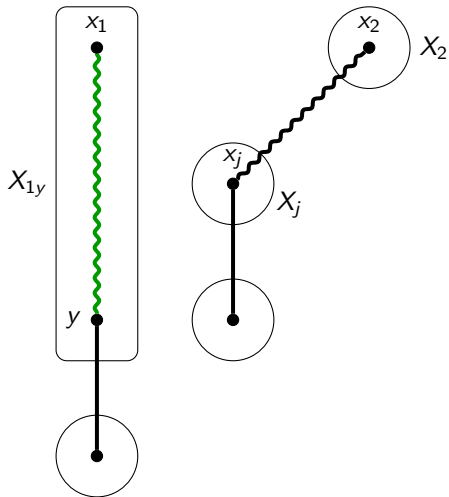
Sample case – Two children



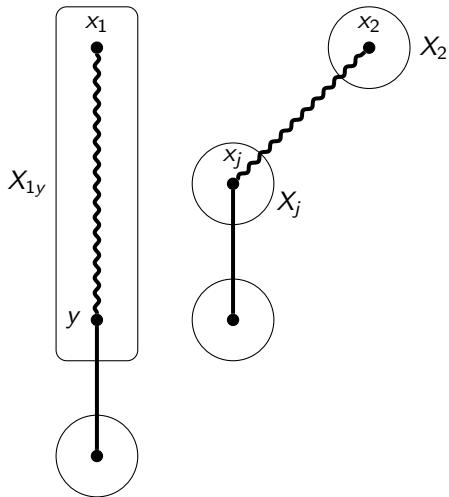
Sample case – Two children



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$(1, k)$ -trees – Summary

2-edge-connectivity + disjoint 'source' of degree = spanning $(1, \ell)$ -tree.

Corollary

For every $\ell \geq 1$, there exists k_ℓ such that if $G = (V, E)$ is a 2-edge-connected graph and H is some additional graph on V with minimum degree k_ℓ , then $G \cup H$ is spanned by a $(1, \ell + 1)$ -tree T where $d_T(v) \leq d_H(v)$ for every $v \in V$.

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Proof: First deduce a subcubic $(1, 2)$ -tree T_2 spanning G . Then consider a sequence of disjoint small fraction $H_1, \dots, H_{\ell-1}$ of H , where each H_i is an ε_i -fraction of H . By the assumption on k_ℓ , we can assume $\varepsilon_{i+1} \geq 4\varepsilon_i$.

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Using H_1 , from T_2 we can deduce a $(1, 3)$ -tree T_3 spanning G . Note that $d_{T_3}(v) \leq d_{T_2}(v) + d_{H_1}(v)$ for every vertex $v \in V$. Since $4d_{H_1}(v) \leq d_{H_2}(v)$, we can use H_2 to extend T_3 to a $(1, 4)$ -tree T_4 spanning G . Due to the choice of the ε_i 's, this process can be repeated until we get T . ■

Path-trees in bipartite graphs

Path-trees with paths of lengths multiple of ℓ ?

Theorem

For every even $\ell \geq 2$, there exists k_ℓ such that if $G = (V, E)$ is a 2-edge-connected bipartite graph with vertex partition (A, B) and H is some additional bipartite graph with vertex bipartition (A, B) and minimum degree k_ℓ , then $G \cup H$ admits a $(\ell, 2\ell)$ -tree T spanning A where $d_T(v) \leq d_H(v)$ for every $v \in V$.

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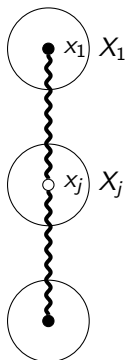
We may assume $4\varepsilon \leq 1/5^p$, where $p = \lceil \log_2 \ell \rceil$. Also, we can deduce a $1/5^p$ -dense 2^p -path-graph H' on H with multiplicity at most $1/16 \cdot 2^p$. Orienting H'^* in a balanced way, every vertex v is the origin of at least $d_H(v)/2.5^p$ private 2^p -paths of H' (with multiplicity at most $1/8 \cdot 2^p$). Furthermore, $2^p \geq \ell - 1$.

Path-trees in bipartite graphs

To obtain T , we once again start from every vertex v of A being its own $(\ell, 2\ell)$ -tree X_v . We then iteratively consider a leaf u in T' with parent x , and concatenate the path associated to ux with some private $(\ell - 1)$ -path of x . This forms an ℓ or 2ℓ -path. ■

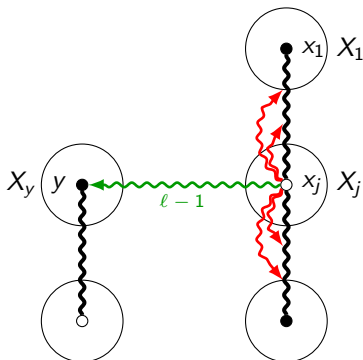
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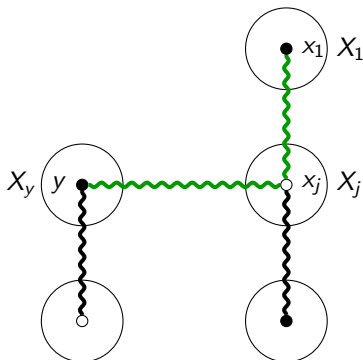
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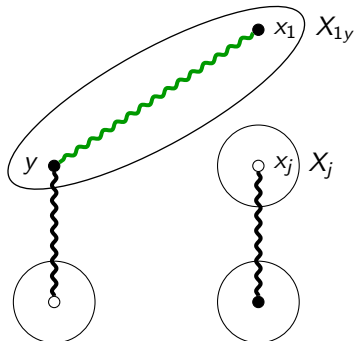
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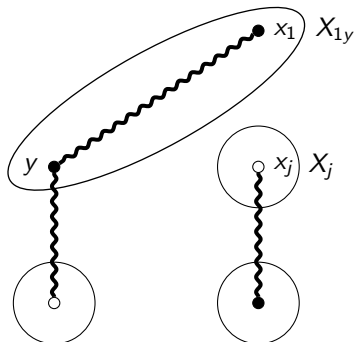
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Refined to...

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2. Make H conflictless eulerian by removing some P_ℓ 's.
3. Achieve the decomposition by following the conflictless eulerian trail.

Remark: We may suppose ℓ is even.

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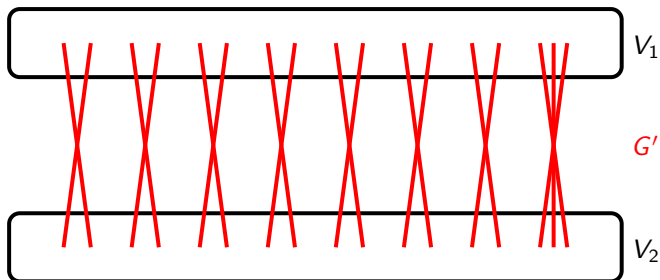
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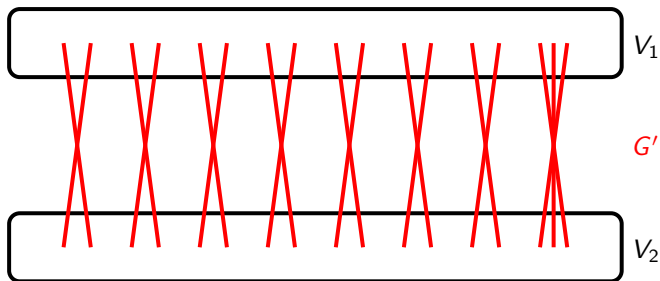


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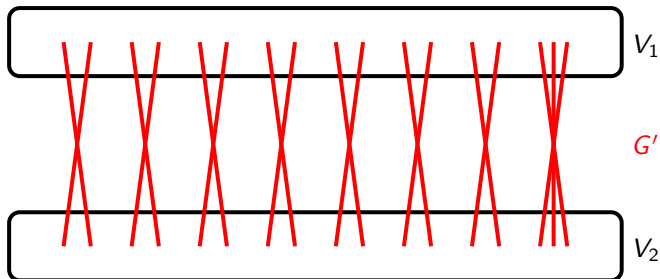
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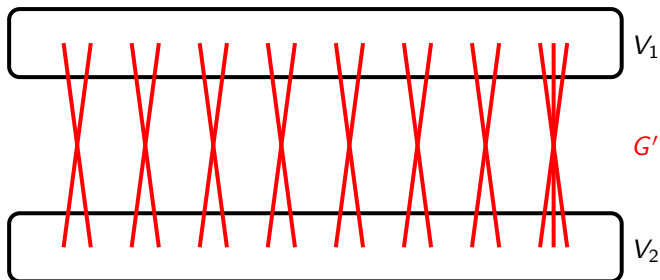
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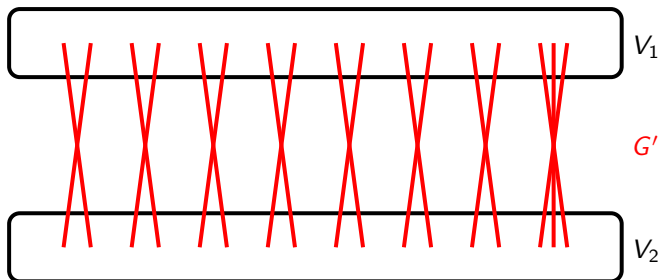
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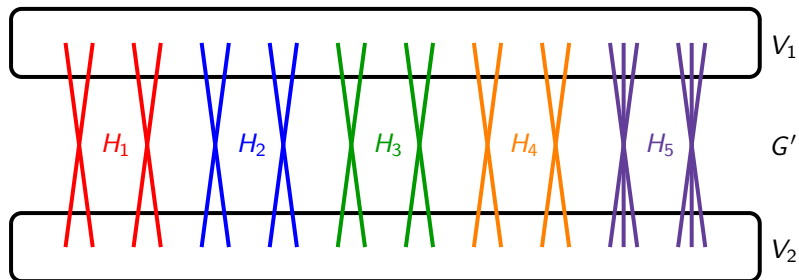
\Rightarrow there exist T_1, \dots, T_8 1/2-sparse spanning trees.

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Set $H_1 := T_1 \cup T_2$, $H_2 := T_3 \cup T_4$, $H_3 := T_5 \cup T_6$, $H_4 := T_7 \cup T_8$, and H_5 the rest.

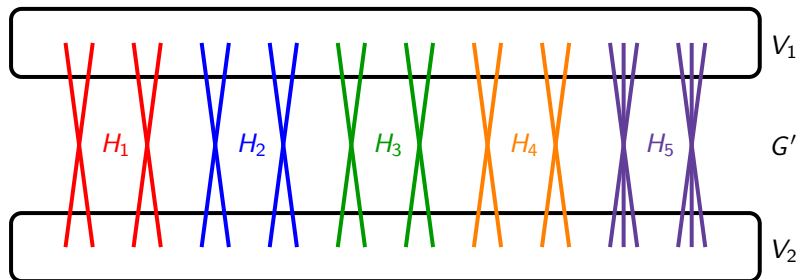
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$$G' = \underbrace{H_1, H_2, H_3, H_4}_{\begin{array}{l} \bullet \text{ connected} \\ \bullet \text{ bridgeless} \\ \bullet \text{ 1/2-sparse} \end{array}} + \underbrace{H_5}_{\begin{array}{l} \bullet \text{ 1/2-dense} \end{array}}$$

Creating $(\ell, 2\ell)$ -trees over V_1 and V_2

H_1 + tiny c -fraction of H_5 = c -sparse $(\ell, 2\ell)$ -tree T'_1 spanning V_1 .

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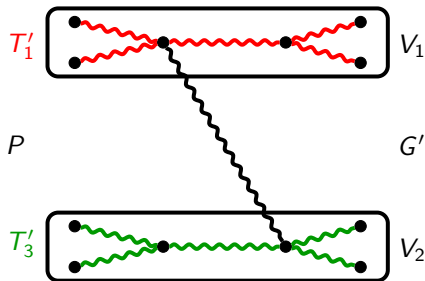
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$T = T'_1 \cup T'_3 \cup P$ is a sparse $(\geq \ell)$ -tree spanning G .



Going on

We may suppose H_5 is still $1/2$ -dense in G' . Because of the degree assumption, it has a $1/5^p$ -dense 2^p -path-graph H with multiplicity at most c , where p satisfies $\ell \leq 2^p < 2\ell$.

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So far, G is decomposed, saved some ℓ -paths, into:

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As long as possible, remove ℓ -paths from R . Call G_R what remains.

Theorem [Thomassen – 2008]

G_R admits a $(< \ell)$ -path-graph with maximum degree at most $\ell - 1$.

Growing the paths of G_R

Call G_R this path-graph.

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Consider a 'tiny' $4c\ell^3$ -fraction of H' of H , and orient H'^* in a balanced way. Then every vertex v is the origin of a private set of $K = 2c\ell^3 d_H(v)$ paths P'_1, \dots, P'_K in H' .

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Call H'_R the resulting ($\geq \ell$)-path graph. In particular, this graph is sparse in H .

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Now, since the multiplicity of H is arbitrarily small and $T \cup T'_2 \cup T'_4 \cup H'_R$ is, say, $4c\ell^3$ -sparse, H_F is a $(\leq 3\ell)$ -path-graph with multiplicity less than $1/24\ell$. Then a conflictless eulerian closed trail exists in H_F . Going along it, we finish the decomposition into ℓ -paths. ■

Part 1: Introduction to the problem

Part 2: Fractions of graphs

Part 3: Path-graphs

Part 4: Constructing path-trees

Part 5: Using everything together

Part 6: Conclusion

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Thank you for your attention.